

EverPump™

Dual Pump control system



User Guide

Revision 1.0

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Table of Contents

| | |
|-----------------------|----|
| Introduction | 4 |
| Operation | 5 |
| LED Status Panel | 6 |
| Master Wiring Diagram | 7 |
| Remote Wiring Diagram | 8 |
| Digital Inputs | 9 |
| Digital Outputs | 9 |
| Relay Connections | 10 |
| Safety Precautions | 11 |
| Warranty | 12 |

Introduction

The Dual-Channel wireless pump control system has been designed to control two remote pumps from a single Tank Unit.

The Tank unit connects to a HIGH level float switch and a LOW level float switch.

The Tank unit will switch the Pumps ON when the level drops below the LOW level float and switch the Pumps OFF when the level rises above the HIGH level float.

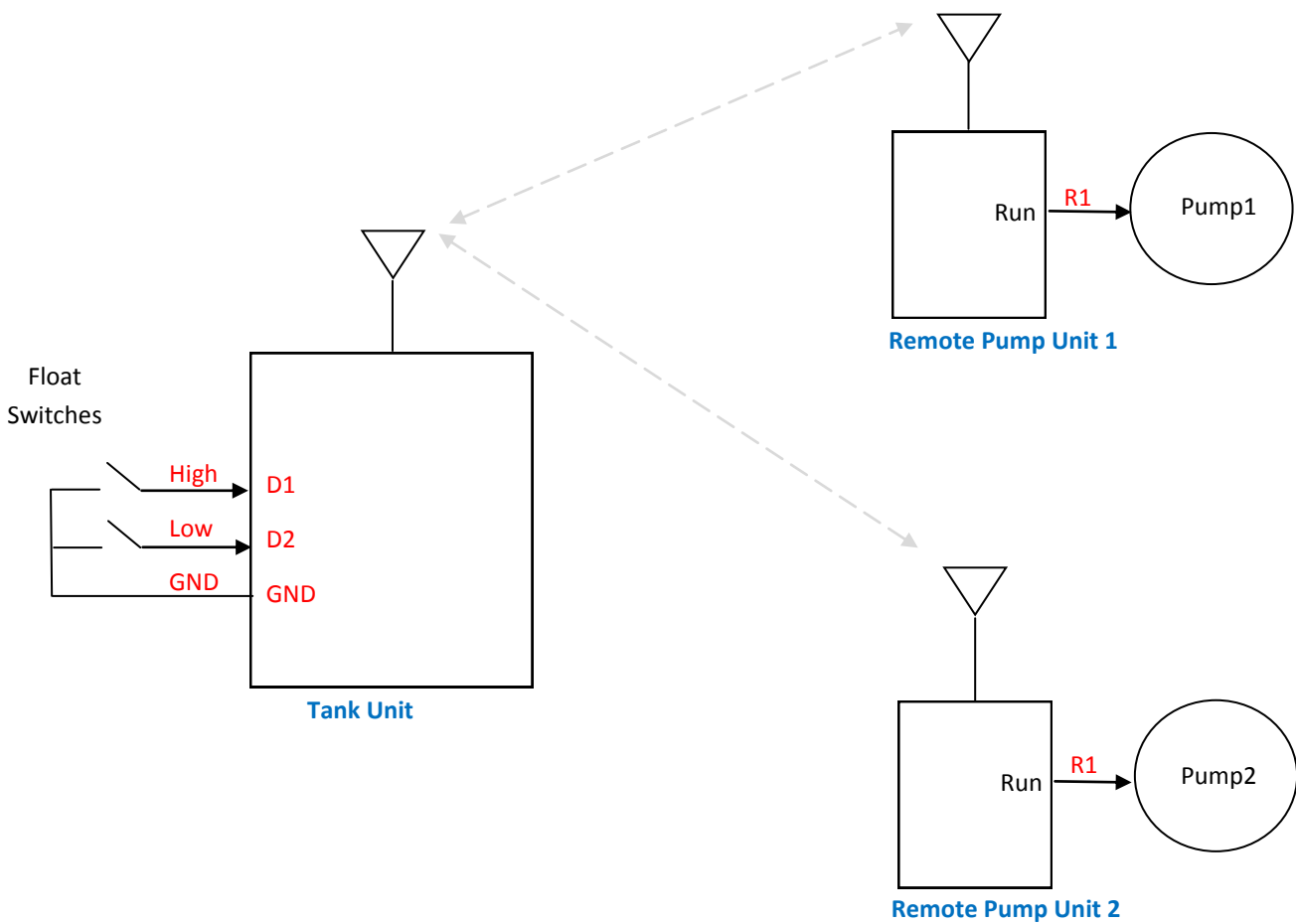


Figure 1. System Overview Diagram

Operation

1. Tank Unit Reads High and Low Float Switches

The High Float switch is connected to “D1” and the Low Float switch to “D2” input of the Tank Unit.

The Tank Unit reads the Float switch states approximately every 30 seconds.

2. Master Unit sends RUN State to Remote Unit 1

The Master Unit first sends the Pump RUN signal state to Remote Unit 1.

3. Remote Unit 1 Responds

Remote Unit 1 will switch the pump control relay (connected to “R1”) ON or OFF in accordance with the state of the Pump control input at the Master Unit.

A LOW signal at the Master Unit will cause the Pump control relay to switch ON and a HIGH/FLOATING signal will cause the Pump control relay to be switched OFF.

The Remote Unit will then read the STATUS input (“D1”) and the FAULT input (“D2”)

And immediately send the state of the PUMP, STATUS INPUT and FAULT INPUT back to the Master Unit.

4. Master Unit processes response from Remote Unit 1

The Master Unit will set the STATUS output for Pump 1 (“R1”) and the FAULT output for Pump 1 (“R2”) accordingly. (A HIGH/FLOATING input at remote input will result in corresponding HIGH/FLOATING state at the Master Unit outputs).

5. Sequence steps (2) to (4) Repeat for Remote Unit 2

6. System applies 5 second delay

LED Status Panel

The LED status panel plugs into a 10-way black connector on the left hand side of the Master Unit and Remote Unit controller PCB. This board provides indication of the link activity and states of Pumps.

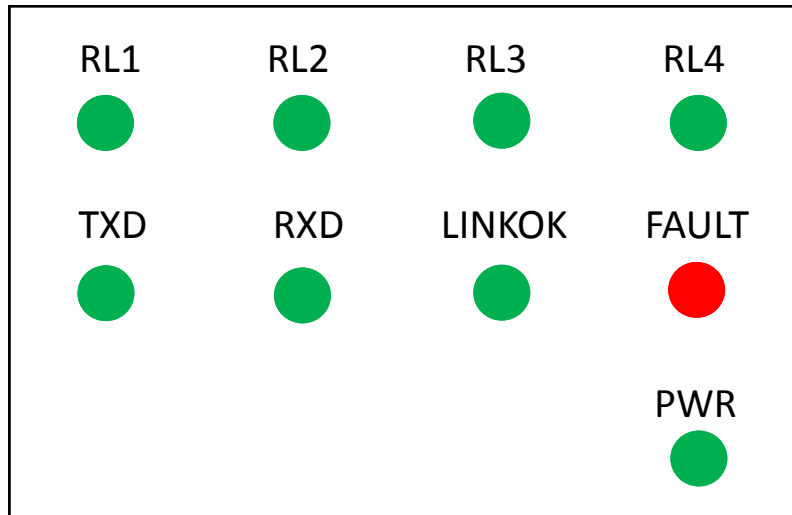


Figure 2. LED Status Panel

| LED | Description | Function |
|--------|--------------------|--|
| RL1 | Pump 1 Run State | ON = Pump 1 on, OFF = Pump 1 off |
| RL2 | Pump 2 Run State | ON = Pump 2 on, OFF = Pump 2 off |
| RL3 | Remote 1 OK | ON = Remote Unit 1 OK, OFF = No response |
| RL4 | Remote 2 OK | ON = Remote Unit 2 OK, OFF = No response |
| TXD | Transmit Activity | Blinks sending data (5 second interval) to |
| RXD | Receive Activity | Blinks when receiving data from Remote Unit |
| LINKOK | Healthy Radio Link | ON when Radio link OK, OFF if Radio link fault |
| FAULT | Faulty Radio Link | ON when any Radio Fault, OFF when link OK |
| PWR | Power OK | ON when power applied to unit |

Table 1. Functions of LED Status Panel

Note: RL2, RL3 and RL4 not used on Remote LED Status Panels.

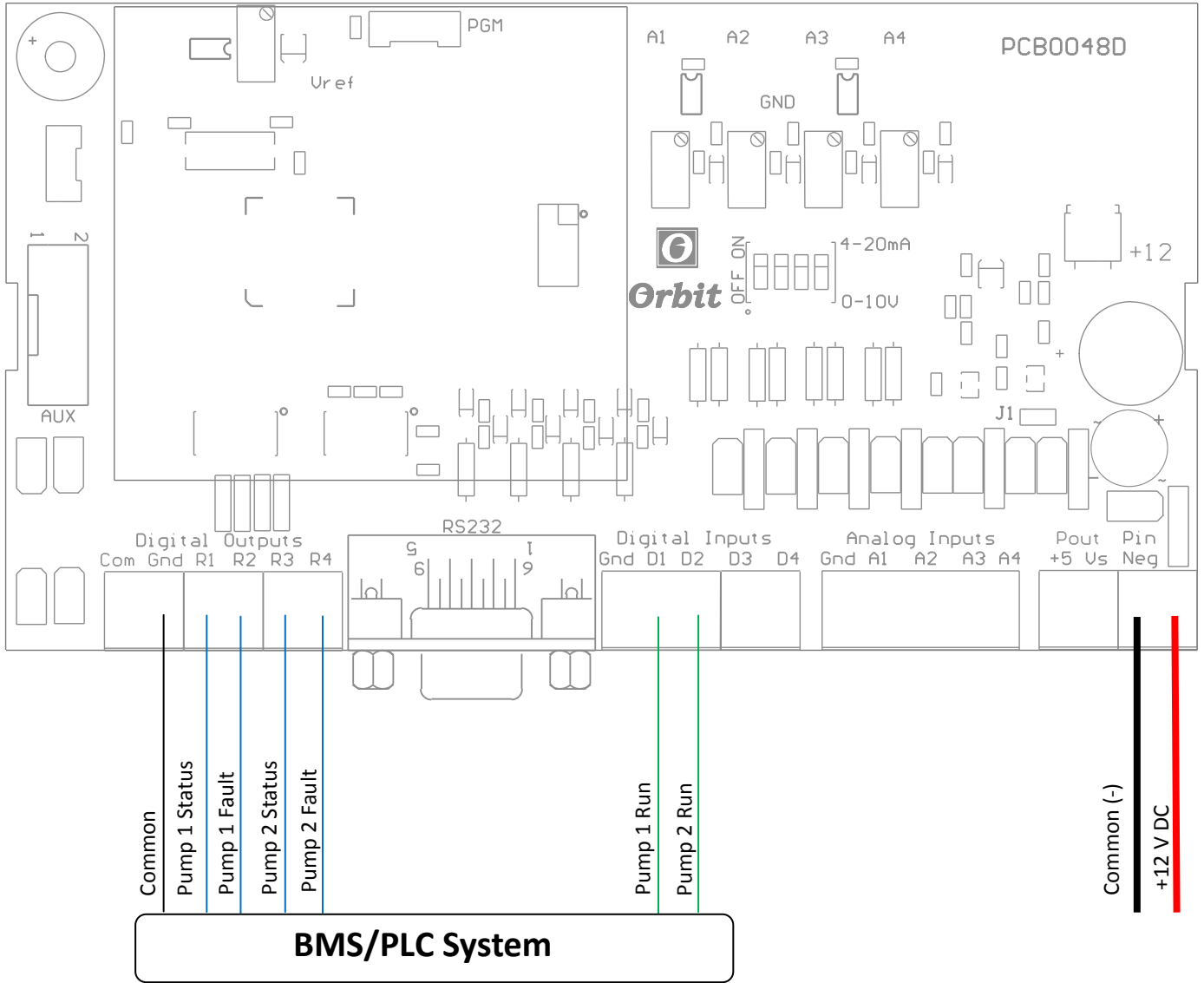


Figure 3. Wiring diagram for Master Unit

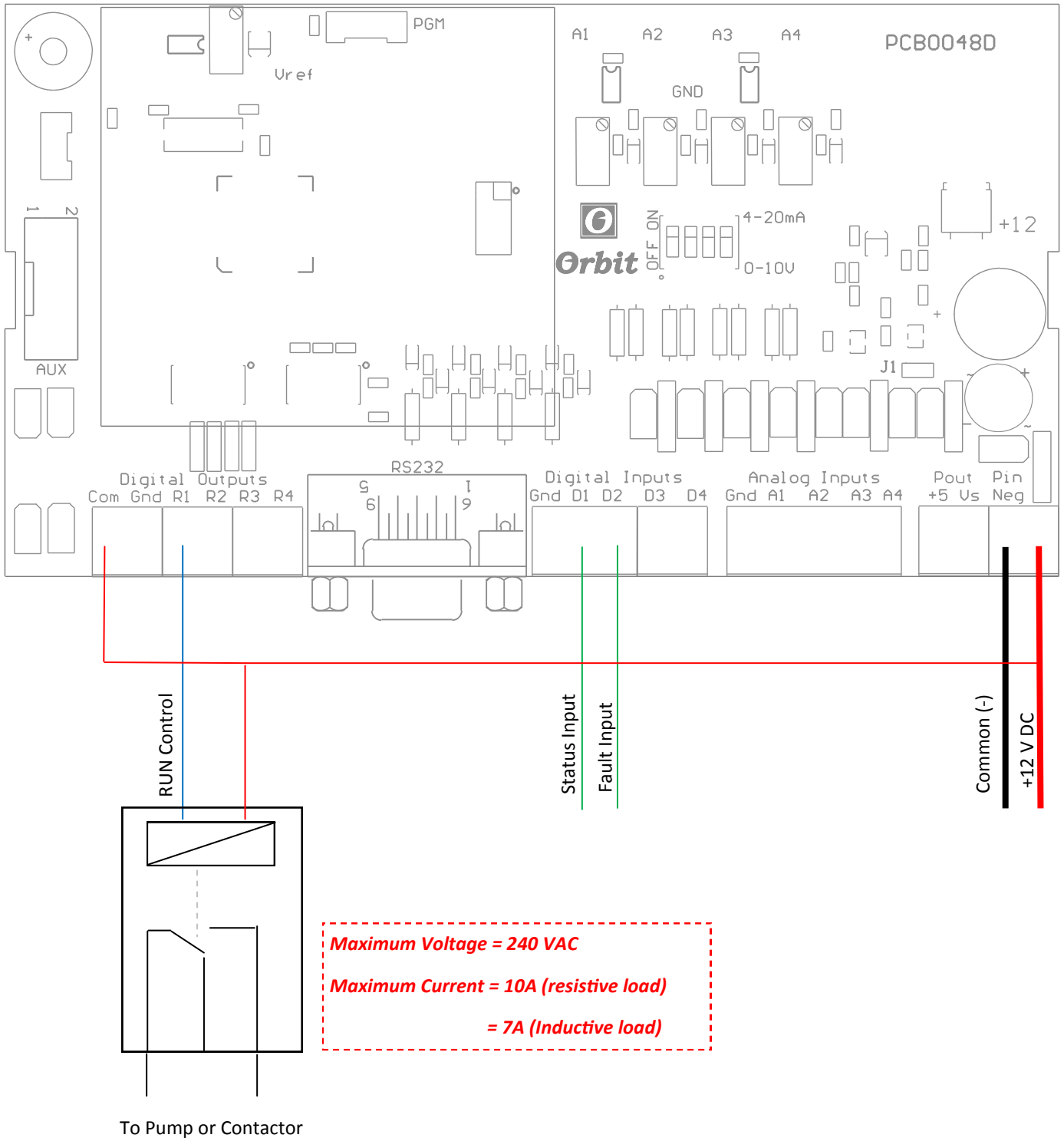


Figure 4. Wiring diagram for Remote Pump Unit

Digital Inputs

The Digital Inputs are pulled up to +5V DC via an internal pull-up resistor. The inputs can tolerate over voltage and reverse polarity voltage to +/- 30V DC. ***Voltages applied outside of this range may cause damage.***

The Digital inputs can be operated using any voltage free contact (such as a Relay contact, open drain or open collector output from another device or a switch), the input can also be connected to a voltage source (recommend 0V to 10V maximum). Note: The Common side of the input devices must connect to the GROUND terminal of the RTU device.

Digital Outputs

The RTU Digital outputs are Open Collector type and can tolerate a maximum applied voltage of 50VDC and a sink maximum current of 500mA.

Typical applications use the Digital outputs to control relay coils. The outputs are also suitable to connect directly to inputs of other devices (such as a PLC) that require Voltage-Free inputs or for driving indicators such as LEDs.

Relay Connections

The supplied relay provides two changeover relay contacts. The recommended method is to connect the Pump or contactor between Normally OPEN (N/O) and Common contacts (either A or B as shown below). The relay contacts are rated up to 240VAC and current handling capacity to 7 Amps for an inductive load (such as a motor) and 10 Amps for resistive loads.

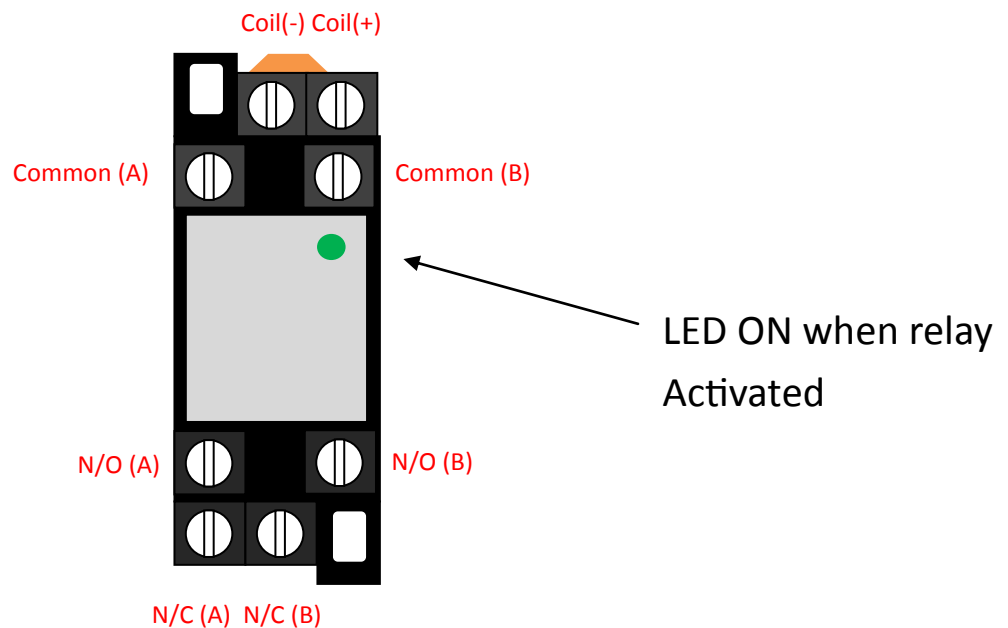


Figure 4. Relay Contact Details

Fitting PCB to DIN Rail

Tilt rear of unit down to enable base to clip onto back of DIN rail

Lower front and press onto DIN rail until locking mechanism clicks into place

Removing PCB from DIN Rail

Use small screwdriver for pull locking TAB (at front of unit) toward you.

Lift Unit up at front and then and away from DIN Rail

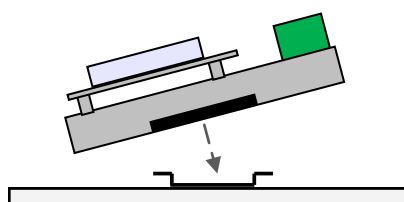


Figure 5. PCB attachment to DIN rail

Safety Precautions

The following safety precautions must be observed whenever the Orbit wireless device system is in operation or in service. Failure to comply with these precautions violates the safety standards of the design, manufacture and intended use of the product

- The system is not to be used:

In hospitals or places where medical equipment may be in use.

In an aircraft (whether on the ground or in the air)

Refuelling points

Explosive areas

- Restricted use of the Orbit wireless device

Near any chemical plant

Near any Fuel depot

The Orbit wireless device system receives and transmits radio frequency energy while switched on, therefore interference can occur if the Orbit wireless device is located near TVs, radios, PCs or any inadequately shielded equipment.

WEEE directive 2002/96/EC, disposal of old electronic equipment

This product shall not be treated as household waste. It must be placed at an appropriate collection point for the recycling of electrical and electronic equipment. By ensuring the correct disposal of this equipment, it will help the environment and human's health. The recycling will help to conserve the natural resources.

Important

Due to the nature of wireless systems, transmission and reception of data can never be guaranteed. Data may be corrupted (i.e. Have errors) or be totally lost at certain times due to the environment, other machinery or malfunction of electronic components. Although significant loss of data are rare when wireless devices such as the Orbit wireless device system are used in a normal manner, Orbit's wireless device system should not be used in situations where failure to transmit or receive data could result in damage of any kind to the user or any other party, including but not limited to personal injury, death or loss of property. Orbit Communications Pty Ltd accepts no responsibility for damages of any kind resulting from errors in data transmitted or received using Orbit's Orbit wireless device systems, or for the failure of the Orbit wireless device system to transmit or receive such data.

Do not operate the Orbit wireless device system in areas where blasting is in progress, where explosive atmospheres may be present, near medical equipment, near life support equipment, or any equipment which may be susceptible to any form of radio interference, in such areas, Orbit's wireless device system must be powered OFF.

Do not operate Orbit wireless device system in any aircraft, whether the aircraft is on the ground or in flight. In an aircraft the Orbit wireless device system must be powered OFF.

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